



Analytic Stability — Lyapunov's Direct Method

Definition 0.1 *The origin of the state space is stable if there exists a region, $S(r)$, such that states which start within $S(r)$ remain within $S(r)$.*

Definition 0.2 *Systems which satisfy Definition 0.1 are asymptotically stable if as $t \rightarrow \infty$, the system state approaches the origin of the state space.*



Analytic Stability

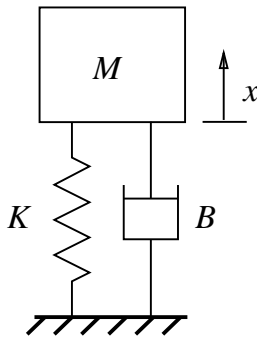
Definition 0.3 Lyapunov's Second Method *If the function, $V(\vec{x}, t)$, exists such that:*

$$\begin{aligned} V(\vec{0}, t) &= 0, \text{ and} \\ V(\vec{x}, t) &> 0, \text{ for } x \neq 0 \text{ (positive definite), and} \\ \partial V / \partial t &< 0 \text{ (negative definite),} \end{aligned}$$

then, the state space described by V is asymptotically stable in the neighborhood of the origin. If a system is stable, then there is a suitable Lyapunov function. If however, a particular Lyapunov function does not satisfy these criteria, it is not necessarily true that this system is unstable.



EXAMPLE: spring-mass-damper



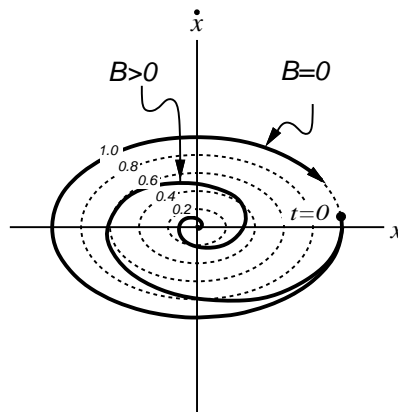
system dynamics:

$$\ddot{x} + \frac{B}{M}\dot{x} + \frac{K}{M}x = 0$$

quadratic Lyapunov function:

$$L = \frac{1}{2}M\dot{x}^2 + \frac{1}{2}Kx^2 \quad \text{positive definite}$$

$$\begin{aligned} \frac{dL}{dt} &= M\dot{x}\ddot{x} + Kx\dot{x} = M\dot{x}\left(-\frac{B}{M}\dot{x} - \frac{K}{M}x\right) + Kx\dot{x} \\ &= -B\dot{x}^2 \quad \text{negative definite} \end{aligned}$$





EXAMPLE: population dynamics

system dynamics:

$$\begin{aligned}x_1 &= \# \text{ males} & \dot{x}_1 &= -x_1 + \alpha x_1 x_2 = x_1(\alpha x_2 - 1) \\x_2 &= \# \text{ females} & \dot{x}_2 &= -x_2 + \beta x_1 x_2 = x_2(\beta x_1 - 1)\end{aligned}$$

equilibrium points: $\dot{\vec{x}} = \vec{0}$

$$\begin{aligned}(\text{a}) \quad & x_1 = x_2 = 0 \\(\text{b}) \quad & x_1 = \frac{1}{\beta}, x_2 = \frac{1}{\alpha}\end{aligned}$$

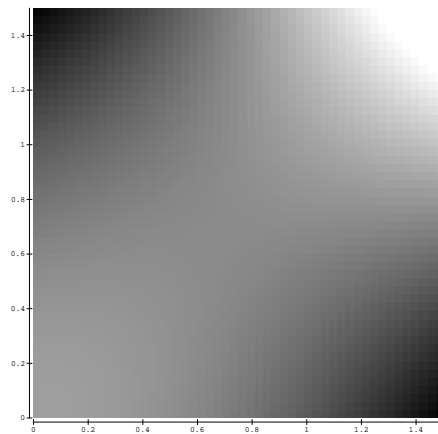
Lyapunov function:

$$\left. \begin{aligned}V(\vec{0}, t) &= 0 \\V(\vec{x}, t) &> 0\end{aligned} \right\} \text{ choose } V(\vec{x}, t) = x_1^2 + x_2^2$$

$$\begin{aligned}\frac{\partial V}{\partial t} &= 2x_1\dot{x}_1 + 2x_2\dot{x}_2 \\&= 2x_1^2(\alpha x_2 - 1) + 2x_2^2(\beta x_1 - 1) \leq 0\end{aligned}$$



EXAMPLE: population dynamics



level curves
in dV/dt function

